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FEB 79 W T ELLISON , J M GARRELICK

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STRUCTURE-BORNE NOISE AND SOUND RADIATION
ASSOCIATED WITH A POINT DRIVEN GRID SUPPORTED
INFINITE PLATE

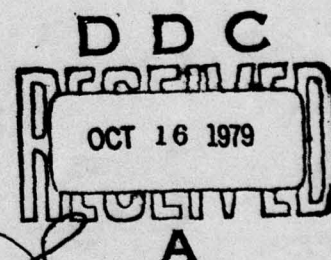
Prepared by:
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and
J. M. Garrelick

February 1979

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Report U-600-260

Prepared for Office of Naval Research
Structural Mechanics - Code 474
800 North Quincy Street
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Attention: N. Basdekas



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20. Abstract (Continued)

any given frequency there always exist some set of structural wave numbers (k_x^0, k_y^0) that represent freely propagating waves. This result is in contrast to previous one-dimensional analyses that result in specific tests of propagating and nonpropagating bands.

The nature of the response of the structure as a function of frequency is provided in terms of the various inertial and elastic properties of the structure, and an analogy is drawn with the one-dimensional result in terms of propagating wave number sets being confronted with an inertial or compliant impedance. The analogy results in the propagating pass bands flipping about the one-dimensional damped-clamped resonant frequencies.

Numerical results are presented comparing the on-axis radiated pressure associated with the one-dimensional and two-dimensional grid structures. For the drive point at a beam location the difference in on-axis radiated pressure is due to the larger inertial impedance of the two-dimensional grid structure.

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ABSTRACT

A general solution has been developed for the transform response and the radiated pressure associated with a fluid loaded, orthogonal grid supported plate driven by a harmonic point force. For the case of light or no fluid loading the solution is in a closed form. A particular interest in developing this solution was to determine the structural pass-band characteristics of such a structure in terms of the inertial and elastic properties of the beams composing the grid as well as the plate itself. It is shown that at any given frequency there always exist some set of structural wave numbers (k_x, k_y) that represent freely propagating waves. This result is in contrast to previous one-dimensional analyses that result in specific sets of propagating and nonpropagating bands.

The nature of the response of the structure as a function of frequency is provided in terms of the various inertial and elastic properties of the structure, and an analogy is drawn with the one-dimensional result in terms of propagating wave number sets being confronted with an inertial or compliant impedance. The analogy results in the propagating pass bands flipping about the one-dimensional clamped-clamped resonant frequencies.

Numerical results are presented comparing the on-axis radiated pressure associated with the one-dimensional and two-dimensional grid structures. For the drive point at a beam location the difference in on-axis radiated pressure is due to the larger inertial impedance of the two-dimensional grid structure.

I. INTRODUCTION

One of the basic building blocks of hull or cabin-like structures is the plating-stringer combination. Typically, machinery induced vibratory forces are applied to a stringer through a foundation structure. The vibration field then propagates along the hull via the hull plating as well as the stringers.

Cremer and Heckl¹ and Mead,² have analyzed the one-dimensional case, i.e., wave propagation in periodically supported, undamped beams. They showed that within discrete frequency bands waves can propagate freely without decay. Outside these "propagation bands," waves decay with distance. The particular problem considered by Mead assumed that the periodic supports offer infinite translational impedances and spring-like rotational constraints. Under the assumption that the excitation is localized to within a single bay, he found that wave motion is produced in the adjacent bays and that these waves are freely propagating within discrete frequency bands. The purpose of this report is to analyze the cut-off frequencies and pass-bands associated with the two-dimensional problem, namely a point driven orthogonal grid structure, and to interpret those results in terms of the propagation of structure-borne noise and the radiation of sound.

II. ANALYSIS

A. General

The structure to be undertaken in this analysis is that of an infinite plate periodically supported by a square orthogonal grid and submerged in a semi-infinite acoustic medium. The problem to be analyzed is the response of this structure to a single harmonic point force applied to the plate at a grid intersection point. Specifically, we will examine "cut-off" phenomena in terms of the various elastic properties of the structure. The subsidiary result for the case of a one dimensional periodic array of beams supporting the plate is also provided.

The geometry utilized in the analysis is depicted in Fig. II-1a and b.

B. Equations of Motion

In the following development we have assumed a harmonic time dependence of the form, $e^{-i\omega t}$. Derivatives with respect to time in the plate and beam equations have thus been taken, and the time dependence factored out.

1. Thin Plate Equations - Assuming that the force is applied at the origin which is also a grid intersection point, then the equation of motion is,

$$[D\nabla^4 - m_p \omega^2] w_p(x, y) = F_0 \delta(x) \delta(y) + \sum_{n=-\infty}^{\infty} Q(x, y) \delta(x-nL) \quad (II-1)$$

$$+ \sum_{m=-\infty}^{\infty} Q(x, y) \delta(y-mL) + p(x, y)$$

where

$$D = E_p h_p^3 / 12(1 - \nu_p^2)$$

E_p = Plate modulus of elasticity

h_p = Plate thickness

ν_p = Poisson's Ratio

$$m_p = \rho_p h_p$$

$$\rho_p = \text{Density of plate}$$

$$k_f^4 = m_p \omega^2 / D$$

$$F_o = \text{Applied Force}$$

$$Q(x,y) = \text{Beam reaction force}$$

$$p(x,y) = \text{Fluid pressure reaction on plate}$$

Upon applying the double Fourier transform to Eq. II-1, we obtain

$$\begin{aligned} LD[(k_x^2 + k_y^2)^2 - k_f^4] \tilde{w}_p(k_x, k_y) = LF_o + \sum_{n=-\infty}^{\infty} \tilde{Q}\left[\left(k_x - \frac{2\pi n}{L}\right), k_y\right] \\ + \sum_{m=-\infty}^{\infty} \tilde{Q}\left[k_x, \left(k_y - \frac{2\pi m}{L}\right)\right] + \tilde{p}(k_x, k_y) \end{aligned} \quad (\text{II-2})$$

where we have utilized the following transform relations,

$$\tilde{f}(k_x, k_y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-ik_x x} e^{-ik_y y} dx dy$$

$$f(x, y) = \frac{1}{4\pi^2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \tilde{f}(k_x, k_y) e^{+ik_x x} e^{+ik_y y} dk_x dk_y$$

$$\sum_{n=-\infty}^{\infty} \int_{-\infty}^{\infty} f(x) \delta(x-nL) e^{-ik_x x} dx = \frac{1}{L} \sum_{n=-\infty}^{\infty} \tilde{f}\left(k_x - \frac{2\pi n}{L}\right)$$

Now for a plate of infinite extent we can also write the transformed surface pressure in terms of the transformed plate displacement.³

$$\tilde{p}(k_x, k_y) = \frac{-i\omega^2 \rho \tilde{w}(k_x, k_y)}{(k^2 - k_x^2 - k_y^2)^{1/2}} \quad (\text{II-3})$$

where

ρ = Density of surrounding fluid

k = Acoustic wave number in fluid (ω/c)

2. Beam (Grid) Equations - We can write two equations for the grid network of orthogonal (Euler-Bernoulli) beams,

$$[E_B I_B \frac{\partial^4}{\partial y^4} - M_B \omega^2] w_p(x, y) \delta(x-nL) = - Q(x, y) \delta(x-nL) \quad (II-4)$$

$$[E_B I_B \frac{\partial^4}{\partial x^4} - M_B \omega^2] w_p(x, y) \delta(y-mL) = - Q(x, y) \delta(y-mL) \quad (II-5)$$

where

E_B = Beam modulus of elasticity

I_B = Beam moment of inertia

$M_B = \rho_B A_B$, mass per unit length of beam

$$k_B^4 = M_B \omega^2 / E_B I_B$$

Applying the double Fourier transform to the two beam equations results in,

$$E_B I_B (k_y^4 - k_B^4) \tilde{w}_p \left[\left(k_x - \frac{2\pi n}{L} \right), k_y \right] = - \tilde{Q} \left[\left(k_x - \frac{2\pi n}{L} \right), k_y \right] \quad (II-6)$$

$$E_B I_B (k_x^4 - k_B^4) \tilde{w}_p \left[k_x, \left(k_y - \frac{2\pi m}{L} \right) \right] = - \tilde{Q} \left[k_x, \left(k_y - \frac{2\pi m}{L} \right) \right] \quad (II-7)$$

C. The Coupled Solution

In developing the solution to the coupled equations of motion (Eqs. II-2, II-6, and II-7) we have defined the following admittance functions,

$$Y_P(k_x, k_y) \equiv \left[LD[(k_x^2 + k_y^2)^2 - k_f^4] - \frac{i\omega^2 \rho L}{(k_x^2 - k_y^2)^{1/2}} \right]^{-1} \quad (\text{II-8})$$

$$Y_B^x \equiv [E_B I_B (k_x^4 - k_B^4)]^{-1}, \quad Y_B^y \equiv [E_B I_B (k_y^4 - k_B^4)]^{-1} \quad (\text{II-9})$$

and adopted the following notation,

$$k_x^n \equiv k_x - \frac{2\pi n}{L}$$

$$k_x^{n,m} \equiv k_x - \frac{2\pi n}{L} - \frac{2\pi m}{L}$$

$$\hat{F}_O \equiv F_O L$$

$$\sum_n \equiv \sum_{n=-\infty}^{\infty}$$

Using these relations we can write the transformed equations of motion as,

$$Y_P^{-1}(k_x, k_y) \tilde{w}_P(k_x, k_y) = \hat{F}_O + \sum_n \tilde{Q}(k_x^n, k_y) + \sum_m \tilde{Q}(k_x, k_y^m) \quad (\text{II-10})$$

$$\tilde{w}_P(k_x^n, k_y) = -Y_B^y \tilde{Q}(k_x^n, k_y) \quad (\text{II-11})$$

$$\tilde{w}_P(k_x, k_y^m) = -Y_B^x \tilde{Q}(k_x, k_y^m) \quad (\text{II-12})$$

Now we wish to solve for the structure displacement response, \tilde{w}_P , in terms of the plate and beam admittance functions, Y_P and Y_B , and the driving force, F_O .

Thus, in Eq. II-10 we first set,

$$k_x = k_x^\ell$$

and then summing both sides over all ℓ , we obtain

$$\begin{aligned} \sum_{\ell} \tilde{w}_p(k_x^{\ell}, k_y^{\ell}) &= \hat{F}_0 \sum_{\ell} Y_p(k_x^{\ell}, k_y^{\ell}) + \sum_{\tilde{n}} \tilde{Q}(k_x^{\tilde{n}}, k_y^{\tilde{n}}) \sum_{\ell} Y_p(k_x^{\ell}, k_y^{\ell}) \\ &+ \sum_{\ell} Y_p(k_x^{\ell}, k_y^{\ell}) \sum_{\tilde{n}} \tilde{Q}(k_x^{\ell}, k_y^{\tilde{n}}) \end{aligned} \quad (\text{II-13})$$

Similarly using Eq. II-10 again but now setting $k_y = k_y^{\ell}$ and summing over all ℓ , we obtain,

$$\begin{aligned} \sum_{\ell} w_p(k_x, k_y^{\ell}) &= \hat{F}_0 \sum_{\ell} Y_p(k_x, k_y^{\ell}) + \sum_{\ell} Y_p(k_x, k_y^{\ell}) \sum_{\tilde{n}} \tilde{Q}(k_x^{\tilde{n}}, k_y^{\ell}) \\ &+ \sum_{\tilde{n}} \tilde{Q}(k_x, k_y^{\tilde{n}}) \sum_{\ell} Y_p(k_x, k_y^{\ell}) \end{aligned} \quad (\text{II-14})$$

In both of these manipulations we have utilized the following identity

$$\sum_{\tilde{n}} A(\tilde{n}) \sum_{\tilde{m}} C(\tilde{n}+\tilde{m}) = \sum_{\tilde{m}} C(\tilde{m}) \sum_{\tilde{n}} A(\tilde{n})$$

Now summing over Eq. II-11, and II-12 we have

$$\sum_{\tilde{n}} \tilde{w}_p(k_x^{\tilde{n}}, k_y^{\tilde{n}}) = -Y_B^Y \sum_{\tilde{n}} \tilde{Q}(k_x^{\tilde{n}}, k_y^{\tilde{n}}) \quad (\text{II-15})$$

$$\sum_{\tilde{n}} \tilde{w}_p(k_x, k_y^{\tilde{n}}) = -Y_B^X \sum_{\tilde{n}} \tilde{Q}(k_x, k_y^{\tilde{n}}) \quad (\text{II-16})$$

Substituting Eq. II-15 into II-13, and II-16 into II-14 yields the following set of equations,

$$\begin{aligned} -Y_B^Y \sum_{\tilde{n}} \tilde{Q}(k_x^{\tilde{n}}, k_y^{\tilde{n}}) &= \hat{F}_0 \sum_{\ell} Y_p(k_x^{\ell}, k_y^{\ell}) + \sum_{\tilde{n}} \tilde{Q}(k_x^{\tilde{n}}, k_y^{\tilde{n}}) \sum_{\ell} Y_p(k_x^{\ell}, k_y^{\ell}) \\ &+ \sum_{\ell} Y_p(k_x^{\ell}, k_y^{\ell}) \sum_{\tilde{n}} \tilde{Q}(k_x^{\ell}, k_y^{\tilde{n}}) \end{aligned} \quad (\text{II-18})$$

$$\begin{aligned} -Y_B^X \sum_{\ell} \tilde{Q}(k_x, k_y^{\ell}) &= \hat{F}_0 \sum_{\ell} Y_p(k_x, k_y^{\ell}) + \sum_{\ell} Y_p(k_x, k_y^{\ell}) \sum_{\tilde{n}} \tilde{Q}(k_x^{\tilde{n}}, k_y^{\ell}) \\ &+ \sum_{\tilde{n}} \tilde{Q}(k_x, k_y^{\tilde{n}}) \sum_{\ell} Y_p(k_x, k_y^{\ell}) \end{aligned} \quad (\text{II-19})$$

To solve for the line reaction transform in terms of the known admittance functions we must make use of the symmetry inherent in the problem. Thus, by symmetry we know,

$$\sum_n \tilde{Q}(k_x^n, k_y) = \sum_n \tilde{Q}(k_y^n, k_x) \quad (\text{II-20})$$

Multiplying both sides by $Y_p(k_x, k_y)$, replacing k_y with k_y^m and summing over all m results in the following identity,

$$\sum_m Y_p(k_x, k_y^m) \sum_n \tilde{Q}(k_x^n, k_y^m) = \sum_n \tilde{Q}(k_x^n, k_y) \sum_m Y_p(k_x, k_y^m) \quad (\text{II-21})$$

In a parallel development we can show that

$$\sum_n Y_p(k_x^n, k_y) \sum_m \tilde{Q}(k_x^n, k_y^m) = \sum_m \tilde{Q}(k_x, k_y^m) \sum_n Y_p(k_x^n, k_y) \quad (\text{II-22})$$

Substituting these two results in Eq. II-18, and II-19 respectively, yields the following pair of equations,

$$-\sum_n \tilde{Q}(k_x^n, k_y) [Y_B^Y + S_x] = \hat{F}_O S_x + S_y \sum_m \tilde{Q}(k_x, k_y^m) \quad (\text{II-23})$$

$$-\sum_m \tilde{Q}(k_x, k_y^m) [Y_B^X + S_y] = \hat{F}_O S_y + S_x \sum_n \tilde{Q}(k_x^n, k_y) \quad (\text{II-24})$$

where

$$S_x \equiv \sum_n Y_p(k_x^n, k_y) \quad (\text{II-25})$$

$$S_y \equiv \sum_m Y_p(k_x, k_y^m) \quad (\text{II-26})$$

Solving Eqs. II-23 and II-24 simultaneously for the transform grid reaction sums and substituting into Eq. II-10 we reach the final result for the transform of the displacement response.

$$\tilde{w}_p(k_x, k_y) = Y_p(k_x, k_y) \hat{F}_O \left[\frac{1}{1 + \frac{Y_B^X S_x + Y_B^Y S_y}{Y_B^X Y_B^Y}} \right] \quad (\text{II-27})$$

D. The Plate Admittance Sums, S_x and S_y

The result provided by Eq. II-27 is limited to numerical computation by the infinite sums of the plate admittance functions. Examining these sums we have from Eq. II-25,

$$S_x = \sum_{n=-\infty}^{\infty} Y_p(k_n^x, k_y) \quad , \quad S_y = \sum_{m=-\infty}^{\infty} Y_p(k_x, k_y^m)$$

where,

$$\begin{aligned} [Y_p(k_n^x, k_y)]^{-1} = LD \left\{ \left[\left(k_x - \frac{2\pi n}{L} \right)^2 + k_y^2 \right]^2 - k_f^4 \right\} \\ - \left\{ \frac{i\omega\rho L}{\left[k^2 - \left(k_x - \frac{2\pi n}{L} \right)^2 - k_y^2 \right]^{1/2}} \right\} \end{aligned} \quad (\text{II-28})$$

We can see that with fluid loading included this sum will be wholly real for values of, $k^2 < k_x^2 + k_y^2$. For values of $k^2 \geq k_x^2 + k_y^2$ the sum will result in both real and imaginary components.

With the fluid loading the sums must be evaluated numerically. There is no problem with convergence but as higher frequencies are considered more terms will be required. In general the number of terms needed is the order of $2k_f L$.

Neglecting the effect of fluid loading, however, the sums are in the form of a quartic in n .

$$S_x = \left(\frac{1}{LD} \right) \left(\frac{L}{2\pi} \right)^4 \sum_{n=-\infty}^{\infty} \frac{1}{p_x(n, f_x, f_y)} \quad (\text{II-29})$$

where,

$$p_x(n, f_x, f_y) = [(f_x - n)^2 + f_y^2]^2 - f_p^4 \quad (\text{II-30a})$$

$$f_x = \frac{k_x L}{2\pi} \quad (\text{II-30b})$$

$$f_y = \frac{k_y L}{2\pi} \quad (\text{II-30c})$$

$$f_p = \frac{k_p L}{2\pi} \quad (\text{II-30d})$$

Now the quartic in the denominator of the sum has four roots

$$p_x(n, f_x, f_y) = (n-p_1)(n-p_2)(n-p_3)(n-p_4) \quad (\text{II-31})$$

where,

$$p_1 = f_x + (f_p^2 - f_y^2)^{1/2}$$

$$p_2 = f_x - (f_p^2 - f_y^2)^{1/2}$$

$$p_3 = f_x + i(f_p^2 + f_y^2)^{1/2}$$

$$p_4 = f_x - i(f_p^2 + f_y^2)^{1/2}$$

Therefore using the residue theorem result⁴

$$\sum_{n=-\infty}^{\infty} p(n) = - \{ \text{sum of the residues of } \pi p(z) \cot \pi z \text{ at the poles of } p(z) \}$$

we can write the result for S_x without fluid loading.

$$S_x = - \left(\frac{1}{LD} \right) \left(\frac{L}{2\pi} \right)^4 \left(\frac{\pi}{4f_p^2} \right) \left\{ \frac{\cot \pi [f_x + (f_p^2 - f_y^2)^{1/2}] - \cot \pi [f_x - (f_p^2 - f_y^2)^{1/2}]}{(f_p^2 - f_y^2)^{1/2}} \right. \\ \left. + \frac{i \cot \pi [f_x + i(f_p^2 + f_y^2)^{1/2}] - i \cot \pi [f_x - i(f_p^2 + f_y^2)^{1/2}]}{(f_p^2 + f_y^2)^{1/2}} \right\} \quad (\text{II-32})$$

The result for S_y is directly obtained by simply switching f_x and f_y in Eq. II-32.

E. The Transform Displacement Response

Using Eq. II-29 with the results just produced, we can write out the transform of the displacement response in a closed form with no infinite sums. The most general expression does not appear to be simply amenable to inverse transformation, however, we can obtain the information on passbands from the behavior of the transform itself. To do this it will be simple and more enlightening to examine our general expression in some of the limiting regions of wavenumber space where the algebraic form of the result is not quite so ponderous. These results are undertaken in the balance of this section.

1. Case #1, $k_f \gg k_x, k_y$ - In this case the plate admittance sums are independent of k_x and k_y ,

$$S_x = S_y = \frac{-k_f}{4m_p \omega^2} \left[\cot \frac{k_f L}{2} + \coth \frac{k_f L}{2} \right] \quad (\text{II-33})$$

$$y_p(k_x, k_y) = - \frac{1}{L m_p \omega^2} \quad (\text{II-34})$$

Assuming the beam wavenumber, k_B , to be of arbitrary magnitude,* we can write our solution directly,

$$\tilde{w}_p(k_x, k_y) = - \frac{F_o}{m_p \omega^2} \left\{ \frac{1}{1 - \frac{\gamma_m}{2} \left[\frac{k_f L}{2} \right] \left[\left(\frac{k_x}{k_B} \right)^4 + \left(\frac{k_y}{k_B} \right)^4 - 2 \right] \left[\cot \frac{k_f L}{2} + \coth \frac{k_f L}{2} \right]} \right\} \quad (\text{II-35})$$

The factor, γ_m , represents the ratio of the beam mass to the plate mass. Thus,

$$\gamma_m = M_B / m_p L$$

* For typical beam/plate combinations the ratio of k_B/k_f would be expected to be less than unity.

2. Case #2, $k_f \gg k_x, k_y$ and $k_B \gg k_x, k_y$ - For this case we can write the answer directly from our previous result, or

$$\tilde{w}_p(k_x, k_y) = - \frac{F_o}{m_p \omega^2} \left\{ \frac{1}{1 + \gamma_m \left(\frac{k_f L}{2} \right) \left(\cot \frac{k_f L}{2} + \coth \frac{k_f L}{2} \right)} \right\} \quad (\text{II-36})$$

Note that Eq. II-36 is also the solution for the very important case of $k_x, k_y = 0$. This solution, related to the on-axis radiated sound pressure, is discussed in greater detail in Section III.

3. Case #3, $k_x, k_y \gg k_f, k_B$, and $k_x L, k_y L \gg 1$ - In this instance we have used the results,

$$\lim_{x, y \rightarrow \infty} \csc^2(x \pm iy) = 0$$

$$\lim_{x, y \rightarrow \infty} \cot(x \pm iy) = \mp i$$

to arrive at greatly simplified expressions for the plate admittance functions,

$$S_x = \frac{1}{4D |k_y|^3}$$

$$S_y = \frac{1}{4D |k_x|^3}$$

and our resultant displacement response is,

$$\tilde{w}_p(k_x, k_y) = \frac{F_o}{m_p \omega^2} \left[\frac{k_f^4}{(k_x^2 + k_y^2)^2} \right] \left[\frac{1}{1 + \frac{\gamma_m}{4} \left(\frac{k_f}{k_B} \right)^4 L (|k_x| + |k_y|)} \right] \quad (\text{II-37})$$

4. Case #4, $k_x = k_y = k_f$ - This particular case, of course, is limited to a single point instead of a region in wavenumber space. There are two solutions with simplified results,

$$a. \quad \underline{k_f L \gg 1}$$

$$\tilde{w}_p(k_x, k_y) = \frac{F_o}{3m_p \omega^2} \left\{ \frac{1}{1 + \frac{\gamma_m}{2\sqrt{2}} \left(\frac{k_f L}{2}\right) \left[\sqrt{2} k_f L \csc^2 \left(\frac{k_f L}{2}\right) - 1 \right] \left[\left(\frac{k_f}{k_B}\right)^4 - 1 \right]} \right\} \quad (II-38)$$

$$b. \quad \underline{k_f L \ll 1}$$

$$\tilde{w}_p(k_x, k_y) = \frac{F_o}{3m_p \omega^2} \left\{ \frac{1}{1 + \frac{5}{6} \gamma_m \left[\left(\frac{k_f}{k_B}\right)^4 - 1 \right]} \right\} \quad (II-39)$$

F. One Dimensional Beam Array

A subsidiary result of the preceding analysis for the grid supported plate is the solution for the point driven plate supported by a one dimensional periodic array of beams (Fig. II-1b).

As the result follows directly from the grid analysis we will simply outline the steps beginning with the transformed equation of motion,

Plate

$$y_p^{-1}(k_x, k_y) \tilde{w}_p(k_x, k_y) = \hat{F}_o + \sum_n \tilde{Q}(k_x^n, k_y) \quad (II-40)$$

Beam

$$y_B^{-1}(k_y) \tilde{w}_p(k_x^n, k_y) = -\tilde{Q}(k_x^n, k_y) \quad (II-41)$$

where y_p^{-1} and y_B^{-1} are given by Eqs. II-8 and II-9. Using the same approach as followed in developing Eqs. II-13 through II-16, we can reach the following result

$$\sum_n \tilde{Q}(k_x^n, k_y) = \frac{-\hat{F}_o S_x}{y_B y + S_x} \quad (II-42)$$

and the transform displacement is

$$\tilde{w}_p(k_x, k_y) = y_p(k_x, k_y) \hat{F}_0 \left[\frac{1}{1 + \frac{S_x}{y_B(k_y)}} \right] \quad (\text{II-43})$$

where S_x is still provided by the result shown in Eq. II-32. As with the grid solution we can develop the following limiting results.

1. Case #1, $k_f \gg k_x, k_y$

$$\tilde{w}_p(k_x, k_y) = - \frac{F_0}{m_p w^2} \left\{ \frac{1}{1 - \frac{\gamma_m}{2} \left[\frac{k_f L}{2} \right] \left[\left(\frac{k_y}{k_B} \right)^4 - 1 \right] \left[\cot \frac{k_f L}{2} + \coth \frac{k_f L}{2} \right]} \right\} \quad (\text{II-44})$$

2. Case #2, $k_f \gg k_x, k_y$ and $k_B \gg k_y$

$$\tilde{w}_p(k_x, k_y) = \frac{F_0}{m_p w^2} \left\{ \frac{1}{1 + \frac{\gamma_m}{2} \left(\frac{k_f L}{2} \right) \left(\cot \frac{k_f L}{2} + \coth \frac{k_f L}{2} \right)} \right\} \quad (\text{II-45})$$

This, of course, is also the result for $k_x = k_y = 0$.

3. Case #3, $k_x, k_y \gg k_f, k_B$ and $k_x L, k_y L \gg 1$

$$\tilde{w}_p(k_x, k_y) = \frac{F_0}{m_p w^2} \left[\frac{k_f^4}{(k_x^2 + k_y^2)^2} \right] \left[\frac{1}{1 + \frac{\gamma_m}{4} \left(\frac{k_f}{k_B} \right)^4 |k_y|} \right] \quad (\text{II-46})$$

4. Case #4, $k_x = k_y = k_f$

a. $\frac{k_f L}{2} \gg 1$

$$\tilde{w}_p(k_x, k_y) = \frac{F_o}{3m_p w^2} \left[\frac{1}{1 + \frac{\gamma_m}{4\sqrt{2}} \left(\frac{k_f L}{2}\right) \left[2\sqrt{2} \left(\frac{k_f L}{2}\right) \csc^2 \left(\frac{k_f L}{2}\right) - 1 \right] \left[\left(\frac{k_f}{k_B}\right)^4 - 1 \right]} \right] \quad (\text{II-47})$$

b. $\frac{k_f L}{2} \ll 1$

$$\tilde{w}_p(k_x, k_y) = \frac{F_o}{3m_p w^2} \left[\frac{1}{1 + \frac{5}{12} \gamma_m \left[\left(\frac{k_f}{k_B}\right)^4 - 1 \right]} \right] \quad (\text{II-48})$$

FIGURE II-1a GRID-SUPPORTED PLATE GEOMETRY

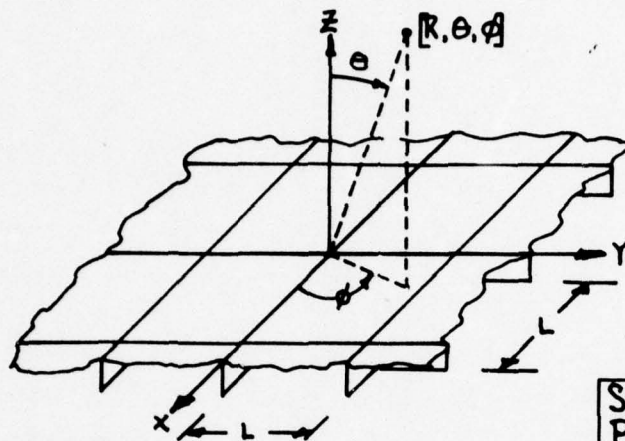


PLATE SUPPORTED BY
PERIODIC GRID OF BEAMS AT:
 $X = \pm nL$, $n = 0, 1, 2, \dots, \infty$
 $Y = \pm mL$, $m = 0, 1, 2, \dots, \infty$

STRUCTURAL PROPERTIES	SYMBOL	
	PLATE	BEAMS
THICKNESS	h_p	—
DENSITY	ρ_p	ρ_b
MODULUS	E_p	E_b
DAMPING	η_p	η_b
SECT. AREA	—	A_b
MOM. INERTIA	—	I_b
DRIV. FORCE	$F_0 e^{-i\omega t}$	

FIGURE II-1b ARRAY-SUPPORTED PLATE GEOMETRY

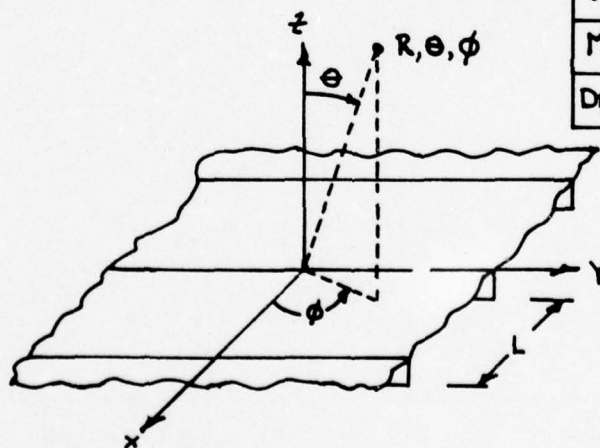


PLATE SUPPORTED BY
PERIODIC ARRAY OF BEAMS AT:
 $X = \pm nL$, $n = 0, 1, 2, \dots, \infty$

III. PASS BAND CHARACTERISTICS

In the analysis section we developed the transform displacement response for two infinitely periodic structures; a plate supported by a one-dimensional array of beams, and a plate supported by a two-dimensional square grid of beams. In both cases the structure was driven by a point force located at a beam support location, and in the grid case at a grid intersection point as well. One of the purposes of this analysis was to determine if such structures exhibited characteristic "pass-bands" within which energy freely propagated from the drive point throughout the structure. In a complementary sense the determination of the existence of non-propagating bands, within which energy was trapped in the bays adjacent to the drive point, was also desired. The purpose of this section will be to determine if such band characteristics exist for the two classes of structures investigated. This is accomplished by investigating the singularities in the wave number spectrum of the plating response. A given frequency will be considered to be within a pass band if, at that frequency, singularities exist which fall on the real (k_x, k_y) axes thus representing undamped propagating waves. Examining the limiting solution $(k_x, k_y \ll k_f)$ as represented by Eq. II-35, we have

$$\tilde{w}_p(k_x, k_y) = \frac{F_o}{m_p \omega^2} \left\{ \frac{1}{1 - \frac{\gamma_m}{2} G(k_f) \left[\left(\frac{k_x}{k_B} \right)^4 + \left(\frac{k_y}{k_B} \right)^4 - 2 \right]} \right\} \quad (\text{III-1})$$

$$G(k_f) = \left(\frac{k_f L}{2} \right) \left[\cot \frac{k_f L}{2} + \coth \frac{k_f L}{2} \right] \quad (\text{III-2})$$

The limits of the propagation bands corresponding to this wavenumber region can be determined from the poles of Eq. III-1. Thus, examining the denominator we see that for a given value of k_y , we can determine the zeroes in terms of k_x , or setting

$$k_y^4 = 2Bk_B^4, \quad B \geq 0 \quad (\text{III-3})$$

then we have

$$k_x = \pm \left[2k_B^4 \right]^{1/4} \left[\frac{1}{\gamma_m G(k_f)} + 1-B \right]^{1/4} \quad (\text{III-4})$$

now, if the quantity within the brackets of Eq. III-4 is positive then k_x will be wholly real, implying a freely propagating wave. (Alternatively if the term within brackets is negative then clearly,

$$k_x = \pm \frac{k_B}{2^{1/4}} (1+i) \left[\left| \frac{1}{\gamma_m G(k_f)} + 1-B \right| \right]^{1/4} \quad (\text{III-5})$$

and the wave will be damped.

For small values of $\gamma_m(1-B)$ the passband limits are closely approximated by the zeroes of $[G(k_f)]^{-1}$, or

$$\text{propagating bands, } n\pi \leq \frac{k_f L}{2} \leq \left(\frac{4n+3}{4} \right) \pi, \quad n = 0, 1, 2, 3, \dots, \infty$$

$$\text{nonpropagating bands, } \left(\frac{4n+3}{4} \right) \pi < \frac{k_f L}{2} < (n+1)\pi, \quad n = 0, 1, 2, 3, \dots, \infty$$

For other values of $\gamma_m(B-1)$ the plate wavenumber limits of the passbands are best described graphically. This result is depicted in Figure III-1 for several representative values of the beam to plate mass ratio parameter, γ_m . Thus, the left hand graph is a plot of $\gamma_m(B-1)$ vs. B for values of $\gamma_m = 1, 5$, and 10. The right hand graph is a plot of $[G(k_f)]^{-1}$ vs. $k_f L/2$. As an illustrative example let us assume that we have a structure with $\gamma_m = 1$. Examining Fig. III-1 we see that for k_y wavenumbers much less than the flexural beam wavenumber k_B , the quantity $\gamma_m(B-1)$ is negative and approximately equal to -1, thus real (propagating) values of k_x will result at all frequencies except those at which

$$[G(k_f)]^{-1} < -1$$

Using the right hand chart then we see that this result corresponds to a series of narrow non-propagating bands, each with a lower bound of

$$\frac{k_f L}{2} = \left(\frac{4n+3}{4} \right) \pi$$

For large values of $\frac{k_f L}{2}$ and values of

$$[\gamma_m(B-1)] \leq -1$$

we can determine an approximate value of the bandwidth, Δ_k , from the expression

$$\cot \left[\Delta_k^{NP} + \left(\frac{4n+3}{4} \right) \pi \right] = \left[\frac{k_f L}{2} \gamma_m(B-1) \right]^{-1} - 1$$

or

$$\Delta_k^{NP} = \frac{1}{1 - k_f L \gamma_m(B-1)}$$

As k_y values nearer to k_B are chosen we see that the bandwidth of the non-propagating bands increases until for,

$$\gamma_m(B-1) > 1$$

most of the frequencies correspond to non-propagating bands with narrow bands of propagating k_x values, each with an upper limit of

$$\frac{k_f L}{2} = \left(\frac{4n+3}{4} \right) \pi$$

The bandwidth in these cases is given by

$$\Delta_k^P = \frac{1}{1 + k_f L \gamma_m(B-1)}$$

The essential result of this analysis is that for any given frequency there always exists some set of (k_x, k_y) wavenumbers which freely propagate. This result has been determined from an analysis of the limiting result for $k_f \gg k_x, k_y$. Examining the other limiting results, as shown in Fig. II-2, we see that none of the expressions shown indicate passband characteristics.

With a one-dimensional structure, however, the results are somewhat different in that a well defined set of pass-bands does exist. The comparable result from our analysis is that provided by the solution for the point driven one-dimensional array as given by Eq. II-44,

$$\tilde{w}_p(k_x, k_y) = \frac{-F_o}{m_p \omega^2} \left\{ \frac{1}{1 - \frac{\gamma_m}{2} \left[\frac{k_f L}{2} \right] \left[\left(\frac{k_y}{k_B} \right)^4 - 1 \right] \left[\cot \frac{k_f L}{2} + \coth \frac{k_f L}{2} \right]} \right\}$$

As the grid problem, the limits of the propagation bands are provided by the poles of this expression, or when

$$k_y = k_B \left(\frac{2}{\gamma_m} \right)^{1/4} \left[\frac{1}{G(k_f)} + \frac{\gamma_m}{2} \right]^{1/4} \quad (\text{III-6})$$

When the quantity in brackets is negative we will have non-propagating wavenumbers given by

$$k_y = k_B \gamma_m^{-1/4} (1+i) \left[\frac{1}{G(k_f)} + \frac{\gamma_m}{2} \right]^{1/4} \quad (\text{III-7})$$

The frequencies at which these will occur are provided by the expression

$$\frac{1}{G(k_f)} \leq -\frac{\gamma_m}{2}$$

and from the result for the grid we can write with minor modification.

A. Propagating Bands

$$1. \quad \frac{\gamma_m}{2} \ll 1$$

$$n\pi \leq \frac{k_f L}{2} \leq \left(\frac{4n+3}{4}\right)\pi, \quad n = 0, 1, 2, \dots, \infty$$

$$2. \quad \frac{\gamma_m}{2} \gg 1$$

$$0 \leq \frac{k_f L}{2} \leq \frac{3\pi}{4}$$

and

$$\left(\frac{4n+3}{4}\right)\pi + \left(\frac{1}{1 + \frac{k_f L \gamma_m}{2}}\right) \leq \frac{k_f L}{2} \leq \left(\frac{4n+3}{4}\right)\pi, \quad n = 0, 1, 2, \dots, \infty$$

B. Non-Propagating Bands

$$1. \quad \frac{\gamma_m}{2} \ll 1$$

$$\left(\frac{4n+3}{4}\right)\pi < \frac{k_f L}{2} < (n+1)\pi, \quad n = 0, 1, 2, \dots, \infty$$

$$2. \quad \frac{\gamma_m}{2} \gg 1$$

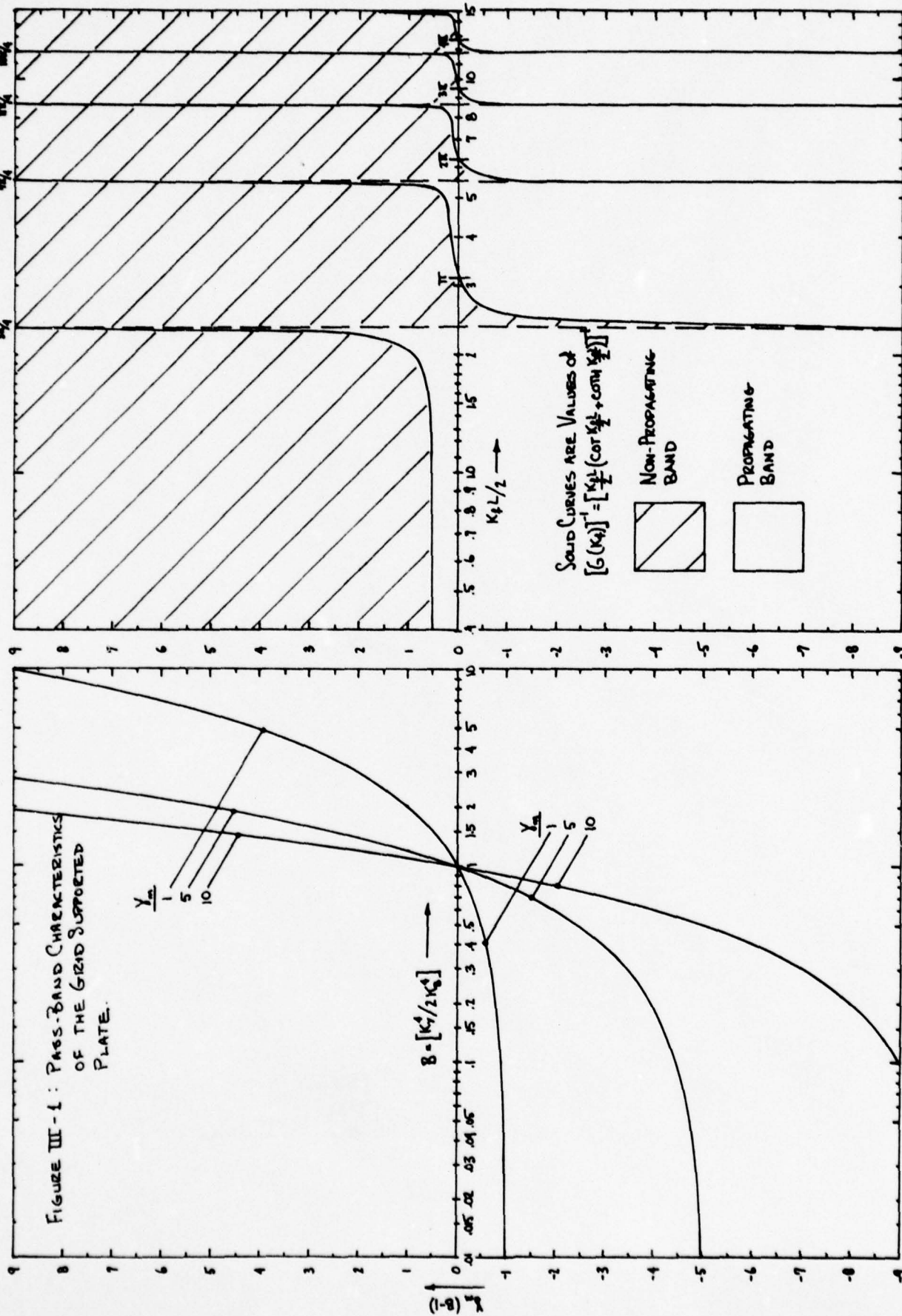
$$\left(\frac{4n+3}{4}\right)\pi < \frac{k_f L}{2} < \left(\frac{4n+3}{4}\right)\pi + \left[\frac{1}{1 + \frac{k_f L \gamma_m}{2}}\right], \quad n = 0, 1, 2, \dots, \infty$$

In comparing this result with the previously cited work by Mead for a one-dimensional beam with a periodic array of rotational restraints, it is noted that the pass-bands just stated for the plate beam array structure

compare with his result for a low rotational inertia--thus, an approximation of a simply supported boundary condition.⁵ In this case he shows that the propagation bands are bounded by the n^{th} simply supported resonance on the low side and the n^{th} clamped-clamped resonance on the upper side. Clearly this is very close to the result just obtained in this analysis for the case $\gamma_m = 0$.

A further comparison with Mead results from a comparison with the solution for spring-like as opposed to mass-like constraints. In the former case the pass-bands flip with the result that the clamped-clamped resonances now determine the lower boundary of the pass-bands. An analogous behavior with the grid supported plate is seen when comparing the pass bands in either low or high (k_y/k_B) regions. Thus at low (k_y/k_B) values the structure represents an inertial-like impedance to waves propagating in the x-direction, and at high k_y/k_B values a compliance like impedance. This analogy becomes somewhat more distinct if we examine the behavior of the $\gamma_m(B-1)$ term in Fig. III-1. Thus, as k_y values from a small fraction of k_B to a large multiple of k_B are traversed we see a clear shift in the sign of the drive point impedance comparable in a qualitative sense to a switch from an inertial to a compliant reactance. It is this periodic shift which directly results in the variance between the one dimensional and two dimensional pass-band results. The relevance of the above results to structure borne noise problems is as follows. For the one dimensional case, the existence of finite band width pass bands and stop bands implies that such a structure can be used as a natural filter to attenuate structure borne noise propagation from a localized excitation. In other words, the one dimensional structure may, in theory, be tuned so that particularly offensive portions of the frequency spectrum of the excitation correspond to stop bands of the structure. However, the two dimensional, or grid, situation is different. Here, there are no stop bands if one assumes that the vibration source exhibits a broad wave-number spectrum such as is produced by a localized vibration source. In other words there is always some portion of the wavenumber spectrum of the excitation that corresponds to a pass-band and thus short circuits the stop band phenomenon. Therefore, in this case, in addition to tuning the frequency

response of the structure to the frequency spectrum of the excitation one must also tune the wavenumber response of the structure to the wavenumber spectrum of the source. Since the wavenumber spectrum of a source is determined largely by the geometrical configuration of its foundation including the structural details of the footings, any attempt to tune a grid structure to take advantage of the existence of stop bands would have to consider such design details.



IV. RADIATED PRESSURE

An interesting and important result directly obtained from the analysis of Section II is the radiated sound pressure measured at a point, (R, θ, ϕ) , θ being measured from the normal to the grid or array supported plate and passing through the drive point location. This result can be written as,⁶

$$p(R, \theta, \phi) = - \rho \omega^2 \frac{e^{ikR}}{2\pi R} \tilde{w}(k \sin \theta \cos \phi, k \sin \theta \sin \phi) \quad (\text{IV-1})$$

Thus, if fluid loading is neglected the far field radiated pressure can be developed in a closed-form using Eqs. II-27 and II-32. In the balance of this section we will examine the effect of various structural configurations on the "on-axis" radiated pressure,

$$p(R, 0, 0) = - \rho \omega^2 \frac{e^{ikR}}{2\pi R} \tilde{w}(0, 0)$$

where $\tilde{w}(0, 0)$ is given in Eq. II-36. We will compare the resultant radiated pressure from four different structural configurations. In making these comparisons we have used a reference pressure, p_o , equivalent to the high frequency limit for the point driven infinite plate.

$$p_o = \frac{\rho F_o}{m_p} \frac{e^{ikR}}{R} \quad (\text{IV-2})$$

A. Point Driven Infinite Plate

This well known result is given by,

$$\left| \frac{p_\infty(R, 0, 0)}{p_o} \right| = \frac{\omega m_p}{\rho c} \left[\frac{1}{1 + \left(\frac{\omega m_p}{\rho c} \right)^2} \right]^{1/2} \quad (\text{IV-3})$$

$$= \frac{\omega m_p}{\rho c}, \quad \omega \rightarrow 0 \quad (\text{IV-4})$$

$$= 1, \quad \omega \rightarrow \infty$$

B. Point Driven Array Supported Plate

Two results are available here, one for the drivepoint at a midspan location,⁷ and the one provided by Eq. II-45 for a drivepoint at a beam support location.

1. Mid Span Drive Point

$$\left| \frac{P_{AM}(R,0,0)}{P_O} \right| = \left| \frac{P_{\infty}(R,0,0)}{P_O} \right| \left\{ 1 - \frac{\frac{1}{\sinh k_f L/2} + \frac{1}{\sinh k_f L/2}}{\frac{2}{\gamma_m \frac{k_f L}{2}} + \cot \frac{k_f L}{2} + \coth \frac{k_f L}{2}} \right\} \quad (IV-6)$$

$$= \frac{\omega_m P}{\rho c} \left[\frac{1}{\gamma_m} \right], \quad \omega \rightarrow 0 \quad (IV-7)$$

$$= 1 - \frac{1}{\cos \left(\frac{k_f L}{2} \right) + \sin \left(\frac{k_f L}{2} \right)}, \quad \omega \rightarrow \infty \quad (IV-8)$$

2. Beam Drive Point

From Eq. II-45 we can write directly,

$$\left| \frac{P_{AB}(R,0,0)}{P_O} \right| = \left| \frac{P_{\infty}(R,0,0)}{P_O} \right| \left[\frac{1}{1 + \frac{\gamma_m}{2} \frac{k_f L}{2} \left(\cot \frac{k_f L}{2} + \coth \frac{k_f L}{2} \right)} \right] \quad (IV-9)$$

$$= \frac{\omega_m P}{\rho c} \left[\frac{1}{1 + \gamma_m} \right], \quad \omega \rightarrow 0 \quad (IV-10)$$

$$= \frac{\gamma_m}{2} \frac{k_f L}{2} \left[\cot \frac{k_f L}{2} + 1 \right], \quad \omega \rightarrow \infty \quad (IV-12)$$

C. Point Driven Grid Supported Plate

As stated in the analysis section the radiated pressure is developed from Eq. II-36. It should be noted that in contrast to the results presented in the analysis section, where the limiting solutions were developed with fluid loading neglected, we have here retained fluid loading to the extent that it is represented in the low frequency limit of the solution. Thus, from Eq. II-8,

$$|y_p(0,0)| = \frac{1}{L\omega^2 m_p} \frac{p_\infty(R,0,0)}{p_o} \quad (\text{IV-13})$$

Using the transform structural displacement from Eq. II-36 we have for the radiated pressure.

$$\left| \frac{p_G(R,0,0)}{p_o} \right| = \left| \frac{p_\infty(R,0,0)}{p_o} \right| \left\{ \frac{1}{1 + \gamma_m \frac{k_f L}{2} \left[\cot \frac{k_f L}{2} \coth \frac{k_f L}{2} \right]} \right\} \quad (\text{IV-14})$$

$$= \frac{\omega m_p}{\rho_c} \left[\frac{1}{1 + 2\gamma_m} \right], \quad \omega \rightarrow 0 \quad (\text{IV-15})$$

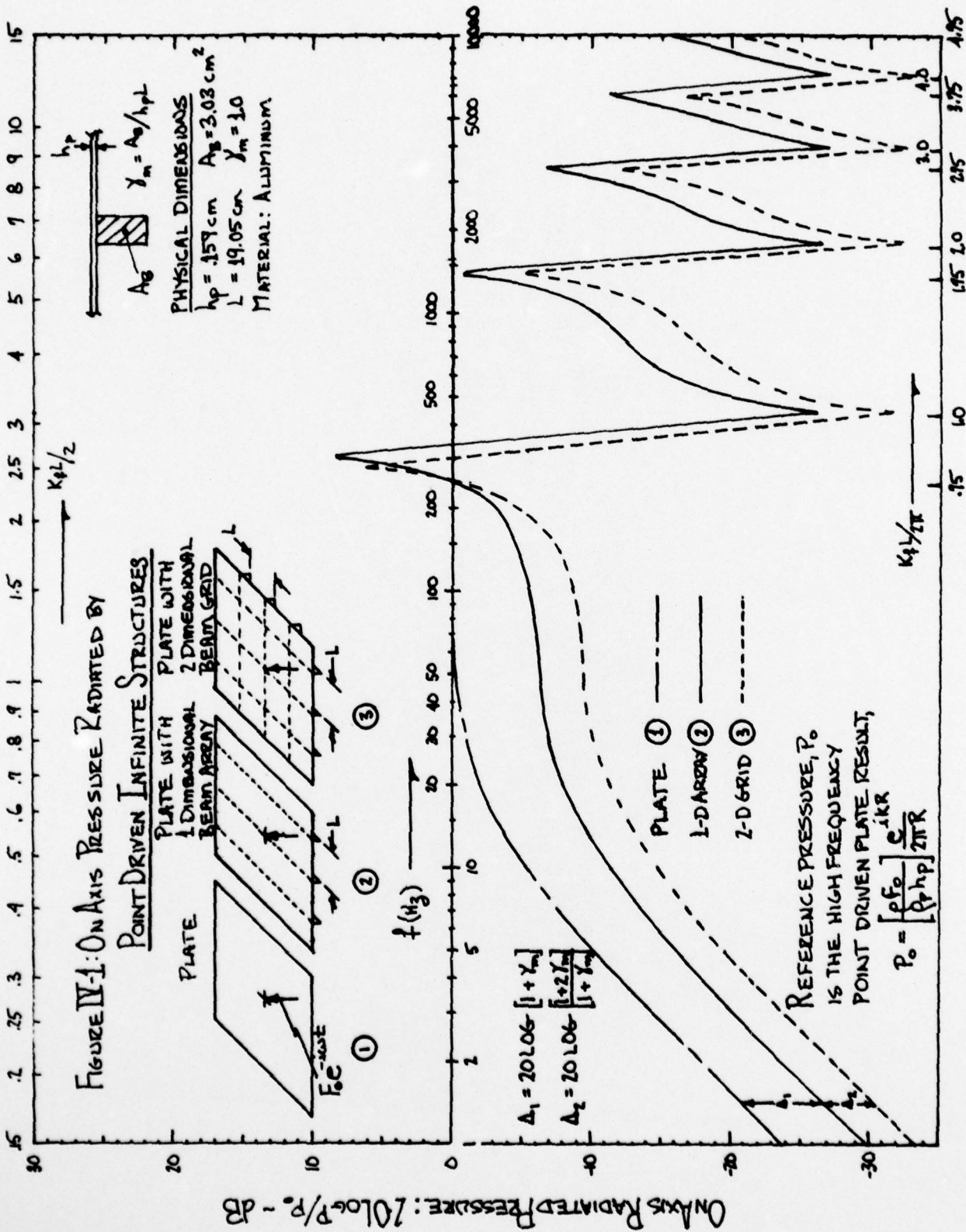
$$= \frac{1}{\gamma_m \frac{k_f L}{2} \left(\cot \frac{k_f L}{2} + 1 \right)}, \quad \omega \rightarrow \infty \quad (\text{IV-16})$$

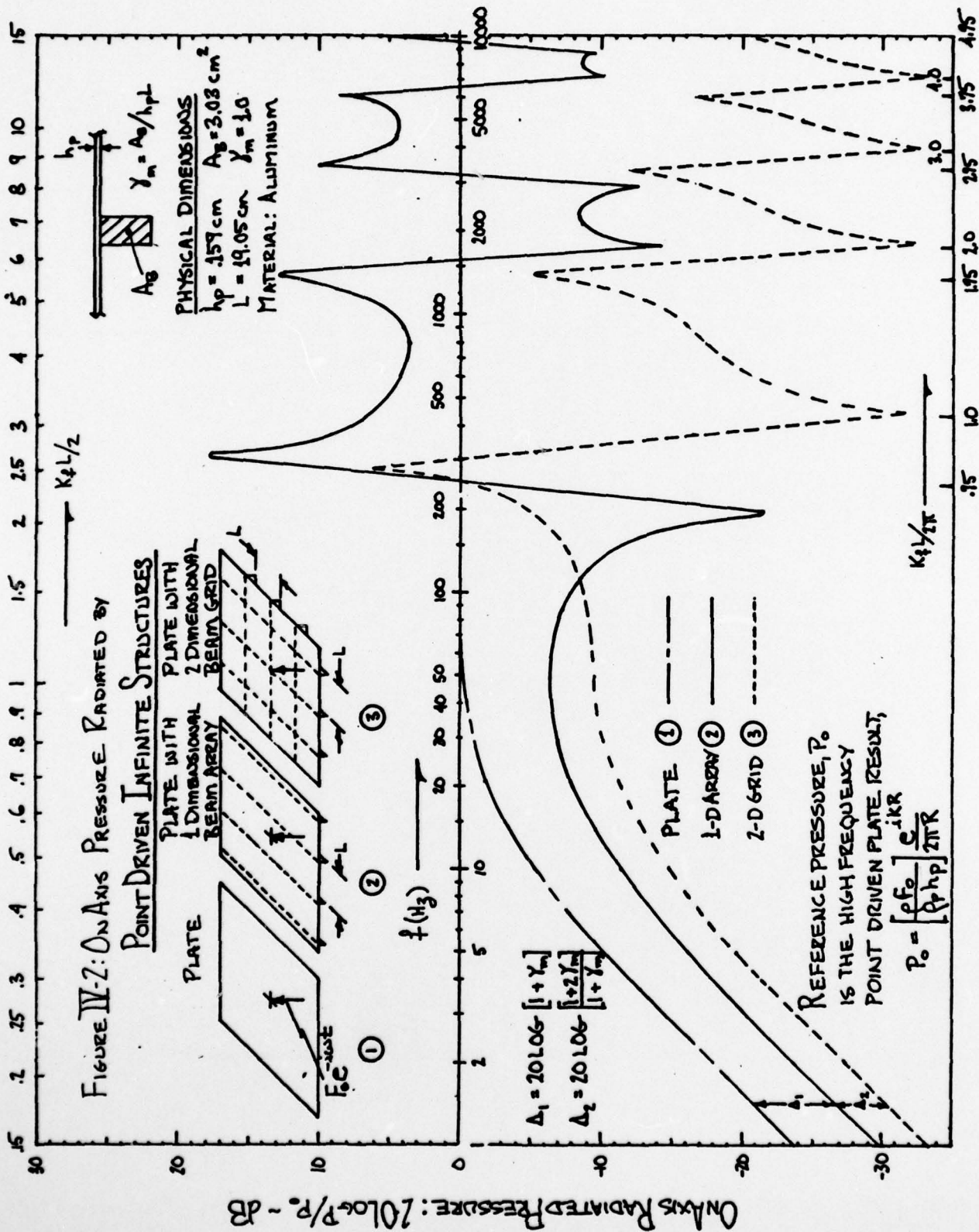
Summaries of these results are shown in Figs. IV-1 and IV-2. The dimensions are typical of airframe structures. A structural damping factor of $\eta_p = .1$ was also used. Several points are of interest to this analysis. At low frequencies the point driven structures differ from the infinite plate result by a factor determined solely by the ratio of beam to plate inertia, γ_m . The actual amounts are shown in each figure.

At high frequencies the point driven structures fall off as $20 \log(f)$ for the beam drive point cases, and approach the infinite plate result, which is frequency independent, for the midspan drive point case. This is due to

the fact that the drive point impedance of a point driven infinite beam is proportional to frequency while that of the infinite plates is frequency independent.

A further point of interest is provided by a comparison with the pass band characteristics determined in Section III. The peaks and valleys in Figs. IV-1 and IV-2 are related to the interframe plating resonances and antiresonances respectively. These plating resonances imply large reactions at the supports adjacent to the drive point which serve to reflect, rather than transmit, incoming waves. Thus the bands corresponding to efficient levels of radiation are very close to the non-propagating bands of the structural analysis.





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Warminster, Pennsylvania 18974
Attn: Aerospace Mechanics
Code 606

U.S. Naval Academy
Engineering Department
Annapolis, Maryland 21402

Naval Facilities Engineering Command
200 Stovall Street
Alexandria, Virginia 22332
Attn: Code 03 (Research and Development)
04B
045
14114 (Technical Library)

Naval Sea Systems Command
Department of the Navy
Washington, D.C. 20362
Attn: Code 05H
312
322
323
05R
32R

Navy (Con't.)

Commander and Director
David W. Taylor Naval Ship
Research and Development Center
Bethesda, Maryland 20084
Attn: Code 042

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Naval Underwater Systems Center
Newport, Rhode Island 02840
Attn: Dr. R. Trainor

Naval Surface Weapons Center
Dahlgren Laboratory
Dahlgren, Virginia 22448
Attn: Code G04
G20

Technical Director
Hare Island Naval Shipyard
Vallejo, California 94592

U.S. Naval Postgraduate School
Library
Code 0384
Monterey, California 93940

Webb Institute of Naval Architecture
Attn: Librarian
Crescent Beach Road, Glen Cove
Long Island, New York 11542

Army

Commanding Officer (2)
U.S. Army Research Office
P.O. Box 12211
Research Triangle Park, NC 27709
Attn: Mr. J. J. Murray, CRD-AA-IP

474:NP:716:lab
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Army (Con't.)

Watervliet Arsenal
MAGGS Research Center
Watervliet, New York 12189
Attn: Director of Research

U.S. Army Materials and Mechanics
Research Center
Watertown, Massachusetts 02172
Attn: Dr. R. Shea, DRXMR-T

U.S. Army Missile Research and
Development Center
Redstone Scientific Information
Center
Chief, Document Section
Redstone Arsenal, Alabama 35809

Army Research and Development
Center
Fort Belvoir, Virginia 22060

NASA

National Aeronautics and Space
Administration
Structures Research Division
Langley Research Center
Langley Station
Hampton, Virginia 23365

National Aeronautics and Space
Administration
Associate Administrator for Advanced
Research and Technology
Washington, D.C. 20546

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Wright-Patterson Air Force Base
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 (FBR)
 (FBE)
 (FBS)
AFML (MBM)

Air Force (Con't.)

Chief Applied Mechanics Group
U.S. Air Force Institute of Technology
Wright-Patterson Air Force Base
Dayton, Ohio 45433

Chief, Civil Engineering Branch
WLRC, Research Division
Air Force Weapons Laboratory
Kirtland Air Force Base
Albuquerque, New Mexico 87117

Air Force Office of Scientific Research
Bolling Air Force Base
Washington, D.C. 20332
Attn: Mechanics Division

Department of the Air Force
Air University Library
Maxwell Air Force Base
Montgomery, Alabama 36112

Other Government Activities

Commandant
Chief, Testing and Development Division
U.S. Coast Guard
1300 E Street, NW.
Washington, D.C. 20226

Technical Director
Marine Corps Development
and Education Command
Quantico, Virginia 22134

Director Defense Research
and Engineering
Technical Library
Room 3C128
The Pentagon
Washington, D.C. 20301

Other Government Activities (Con't) PART 2 - Contractors and Other Technical Collaborators

Dr. M. Gaus
National Science Foundation
Environmental Research Division
Washington, D.C. 20550

Library of Congress
Science and Technology Division
Washington, D.C. 20540

Director
Defense Nuclear Agency
Washington, D.C. 20305
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Mr. Jerome Persh
Staff Specialist for Materials
and Structures
OUSDR&E, The Pentagon
Room 3D1089
Washington, D.C. 20301

Chief, Airframe and Equipment Branch
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Office of Flight Standards
Federal Aviation Agency
Washington, D.C. 20553

National Academy of Sciences
National Research Council
Ship Hull Research Committee
2101 Constitution Avenue
Washington, D.C. 20418
Attn: Mr. A. R. Lytle

National Science Foundation
Engineering Mechanics Section
Division of Engineering
Washington, D.C. 20550

Picatinny Arsenal
Plastics Technical Evaluation Center
Attn: Technical Information Section
Dover, New Jersey 07801

Maritime Administration
Office of Maritime Technology
14th and Constitution Avenue, NW.
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